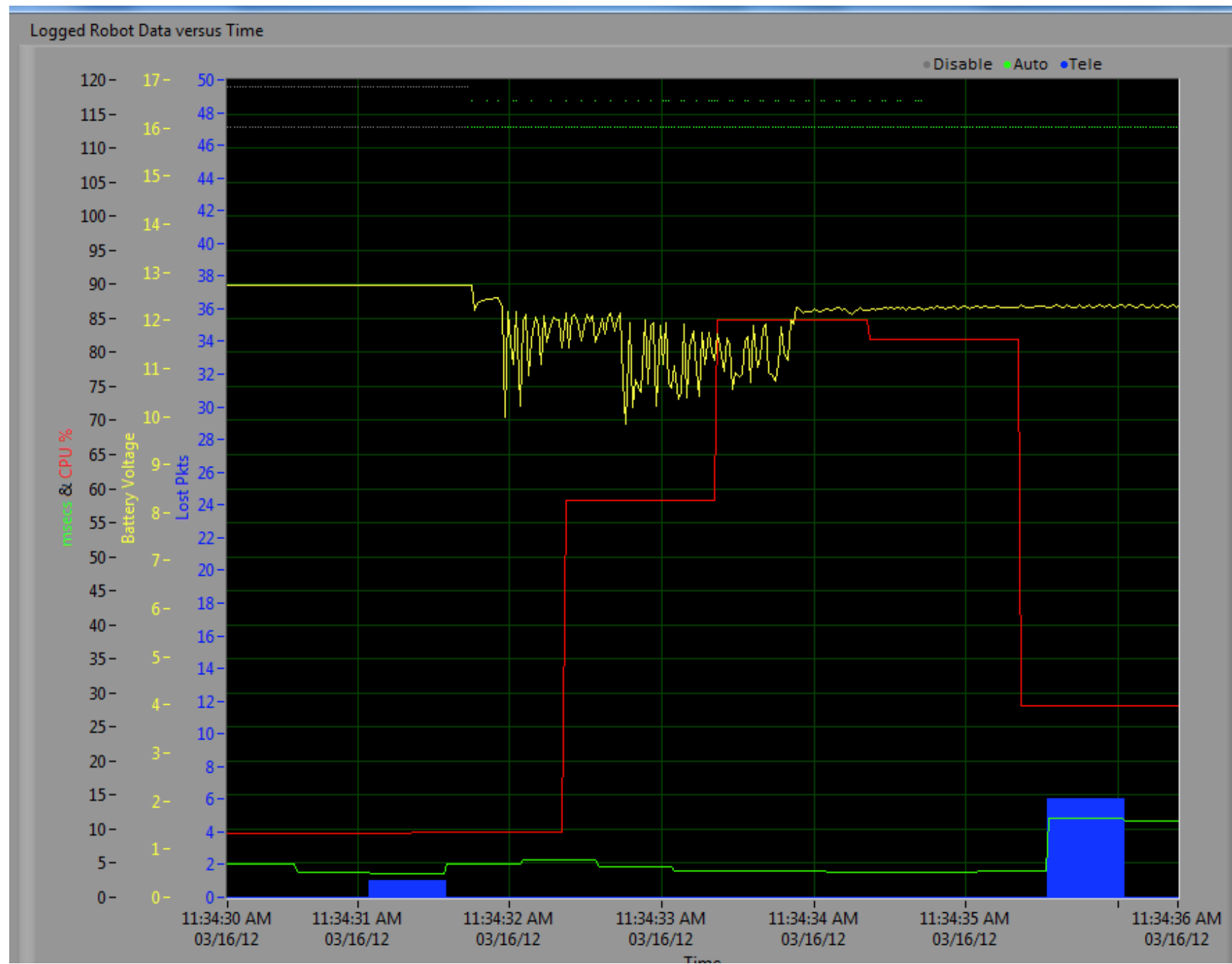
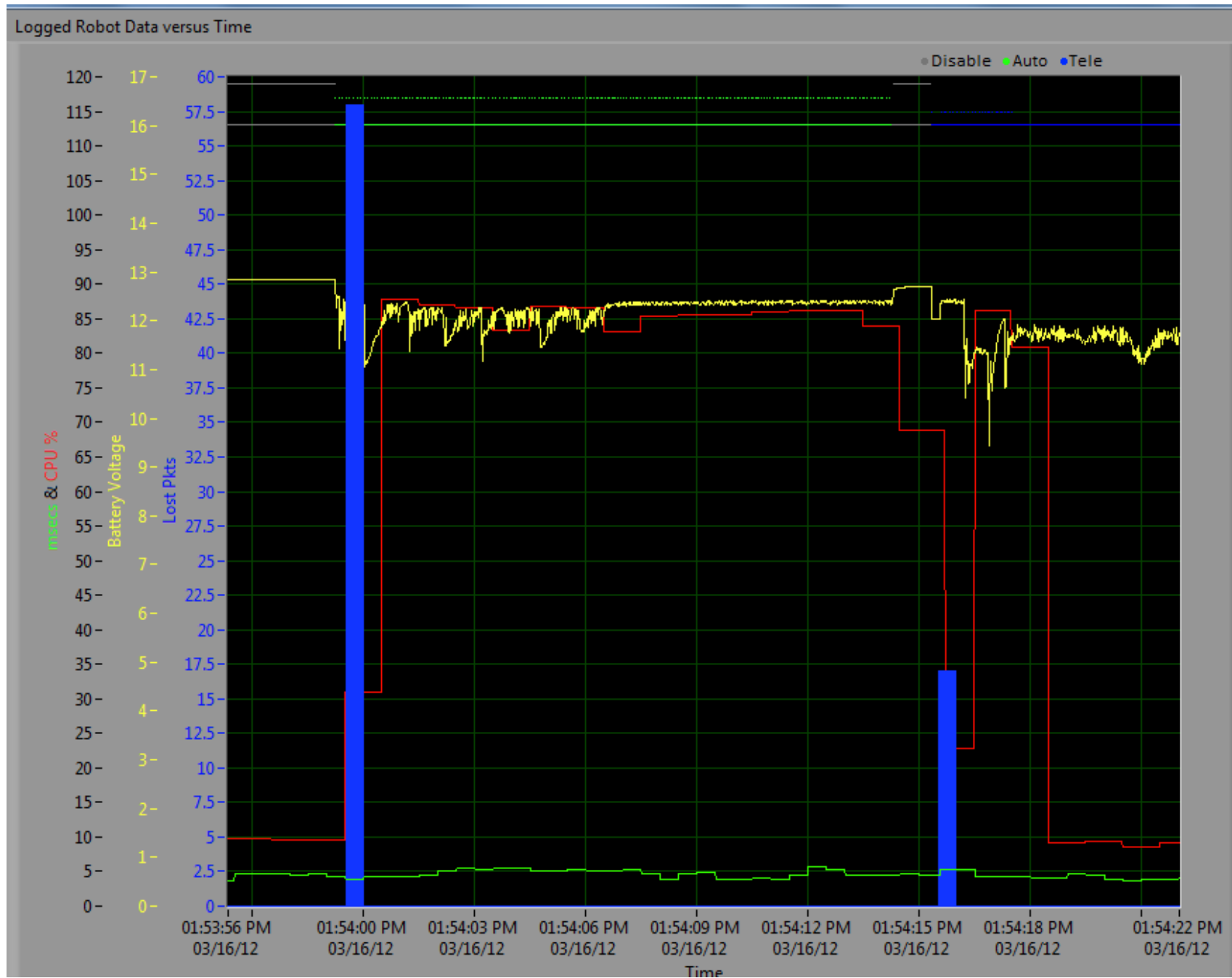


Match 14 - Failed at approximately 3 seconds into autonomous mode (03/16/2012 at 11:33 am)

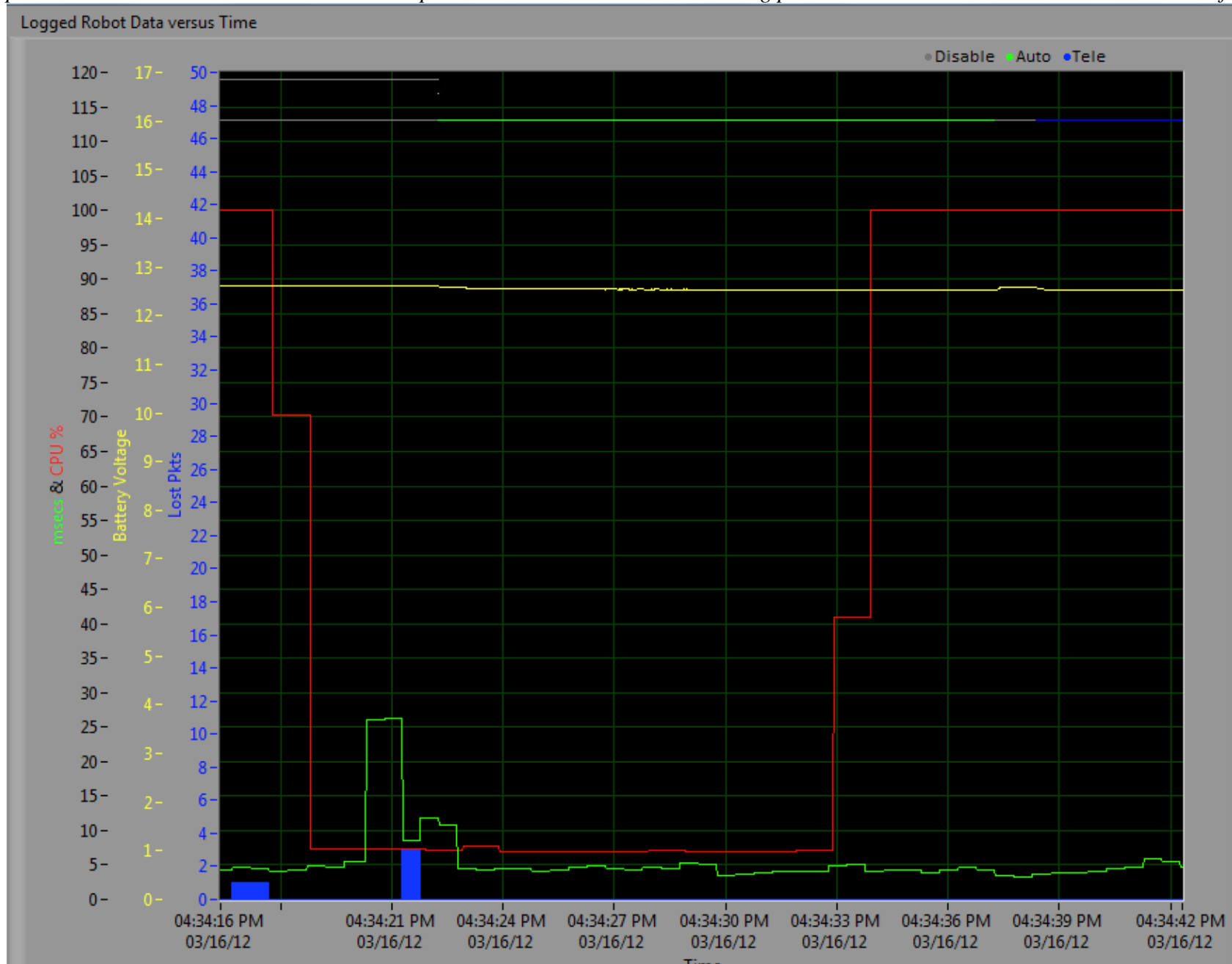


Match 28 - Failed at approximately 3 seconds into teleoperated mode. Robot ran in circles. (03/16/2012 at 1:50 pm)



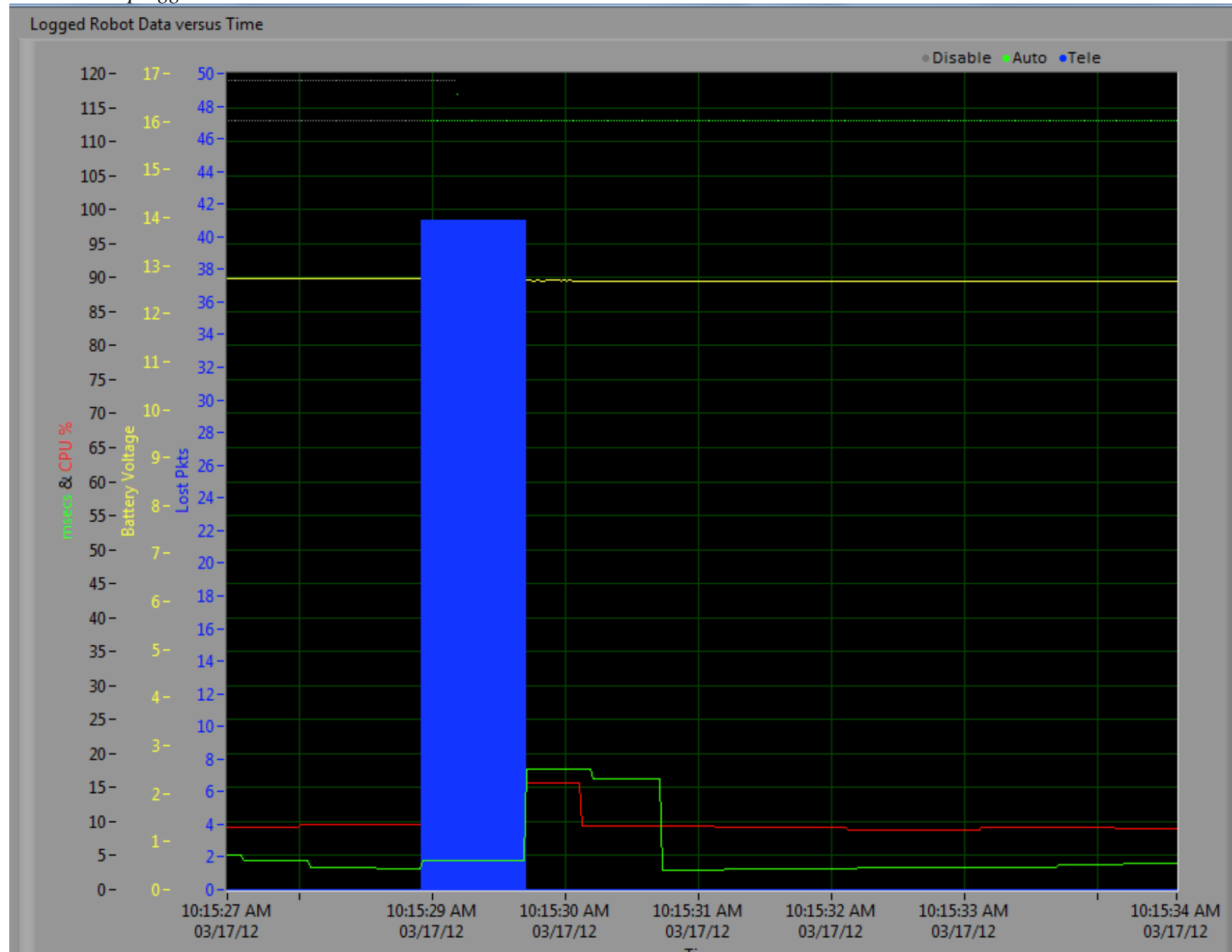
Match 51 - Failed at start of autonomous mode. (03/16/2012 at 4:34 pm)

Note that for this match we intentionally unplugged our camera but left the vision processing in the code. We saw an oscillating CPU pattern where max CPU was at 100%. The prior match had this same oscillating pattern and same max CPU but we ran successfully.



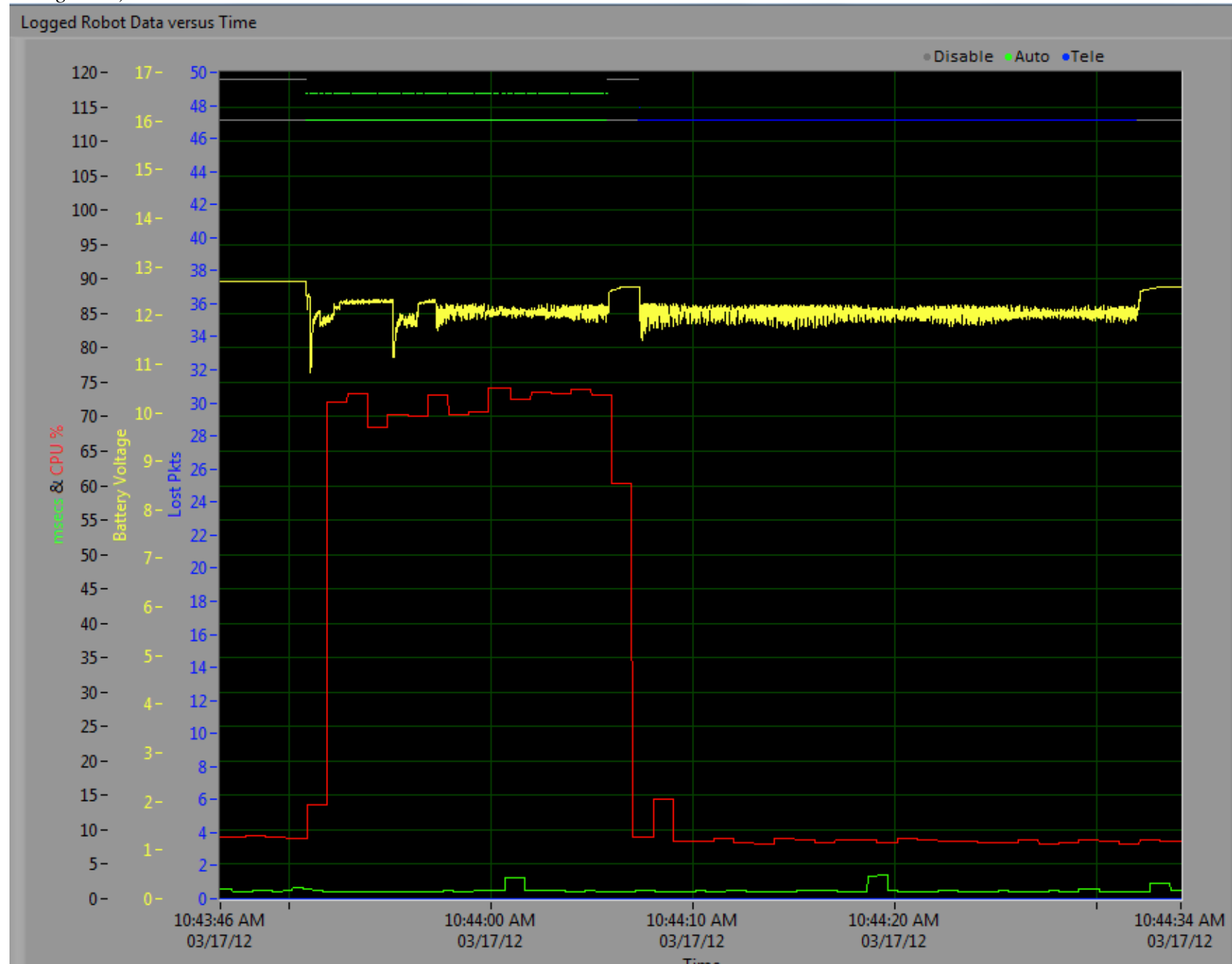
Match 65 - Failed at start of autonomous mode. (03/17/2012 at 10:12 am)

Camera was plugged back in.



Match 70 - Failed at start of teleoperated mode. (03/17/2012 at 10:42 am)

It looks like we lost the ability to control the robot as soon as teleoperated mode started, but that the robot kept doing something (see voltage line) until it was disabled about 20 seconds into the match.



Match 84 - Failed at very beginning of autonomous mode (03/17/2012 at 11:48 am)

