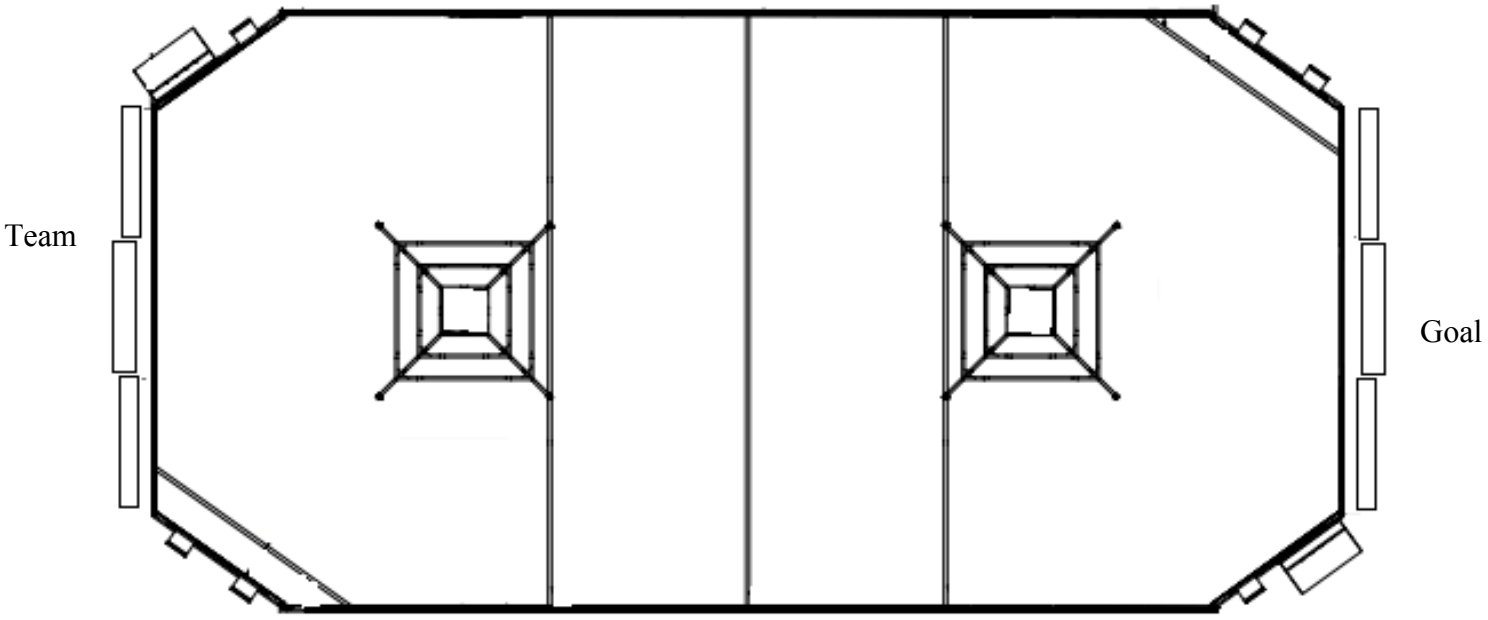
Bit Buckets 4183 **Pit Scouting Sheet** Team #_____
Name_____

Robot Weight: _____lbs Height: _____inches, minimum _____inches, maximum
Shooter height: _____ (inches) *Defensive wallbot? Y / N*
Intake: Can robot pick Frisbees up from the floor? Y / N Feeder intake: Y / N
Drive train Speed: 1st gear_____ 2nd gear_____
# of wheels: 4 or 6 or 8 or other: _____
# of driven wheels: 2 or 4 or 6 or: _____
# of motors driving wheels: _____ Motor types: _____
Wheel style: KOP rubber, treaded, omni, Swerve-drive, AM Mecanum, custom Mecanum, etc.
Scoring: *Anticipated # of Frisbees scored in a match:*
Autonomous: High_____ Medium_____ Low_____
Teleoperated: High_____ Medium_____ Low_____ Pyramid_____
Can your robot score from the feeder slot? Y / N
Climb: 0___ 10____ 20_____ 30_____ Pyramid dump:_____ Climb time:_____ seconds
Consistency of climbing mechanism: _____%
Estimated total point value in: Autonomous: _____ Teleoperated: _____
Mark: A-starting positions, S-scoring positions, P-pyramid climb positions, C-collecting positions
Autonomous: What does the robot do in autonomous? _____



Accuracy: ~% Frisbees that make it into goal: ____%2pt _____%3pt _____%full-court ____%pyramid
Estimated robot practice time driver has had this year: _____days ____hours
Describe offensive strategy:_____
Describe defensive strategy:_____
Problems/ worries with robot?
_____
Robot construction quality: _____
Comments: _____
_____
_____