

# Autonomous Independent.vi

C:\Users\ssmith2\Documents\LabVIEW Data\2010 Game Robot Project - 1-30-10\Autonomous Independent.vi

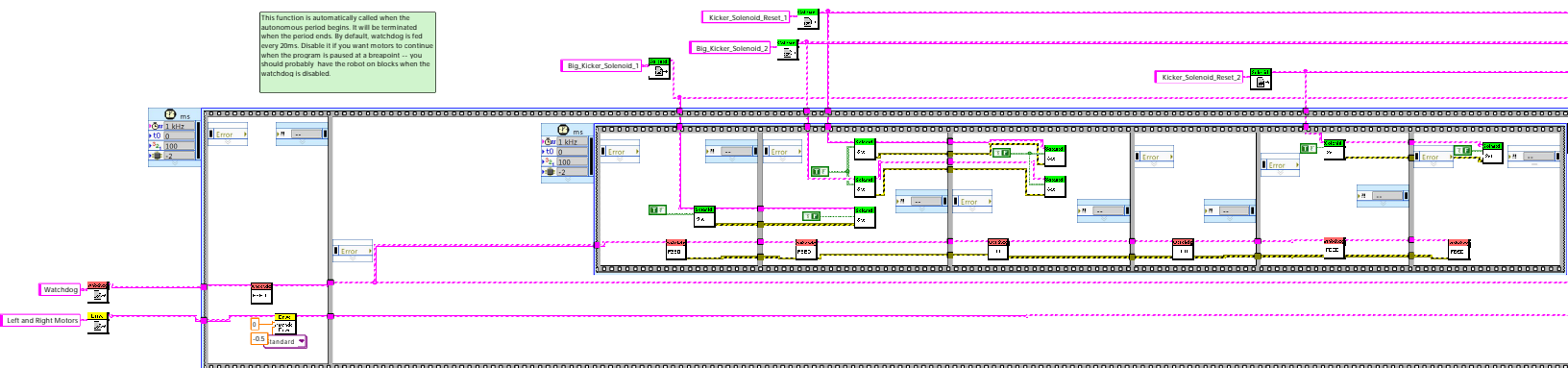
Last modified on 2/27/2010 at 12:59 PM

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This VI is called when autonomous begins, and will automatically be terminated when autonomous ends. You can call out timed or sensor driven robot movement independently without needing to return to the caller.



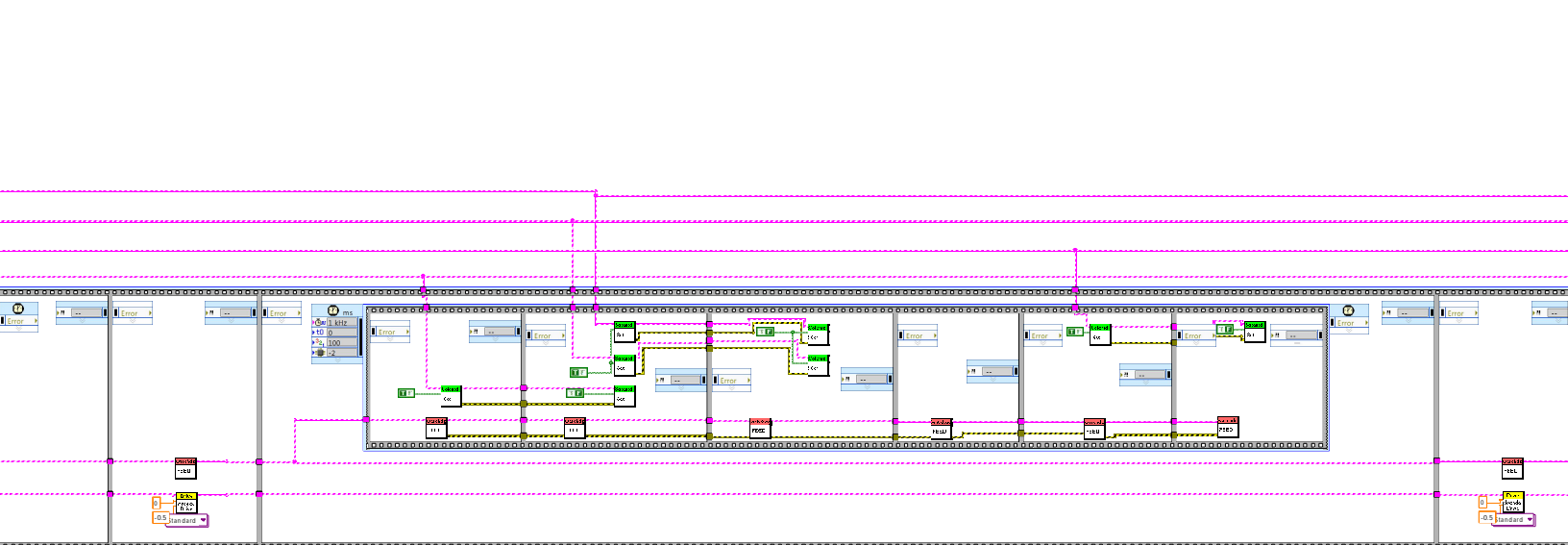
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