

#### Robot Design

#### Robot Design Features

Drive train type:\_\_\_\_\_ Game Piece manipulator:

Tower manipulator (if so describe it):\_

Mechanism to right self:

Mechanism to right alliance partner:

- State what type of drive train your team has
- Describe your team's game piece manipulator

### Robot Design (cont)

#### **Robot Design Features**

Drive train type:\_\_\_\_ Game Piece manipulator:

Tower manipulator (if so describe it):

Mechanism to right self:

Mechanism to right alliance partner:

- Describe your team's righting mechanism if they have one
- Describe your team's mechanism for righting an alliance partner if they have one

#### Strategy and Abilities

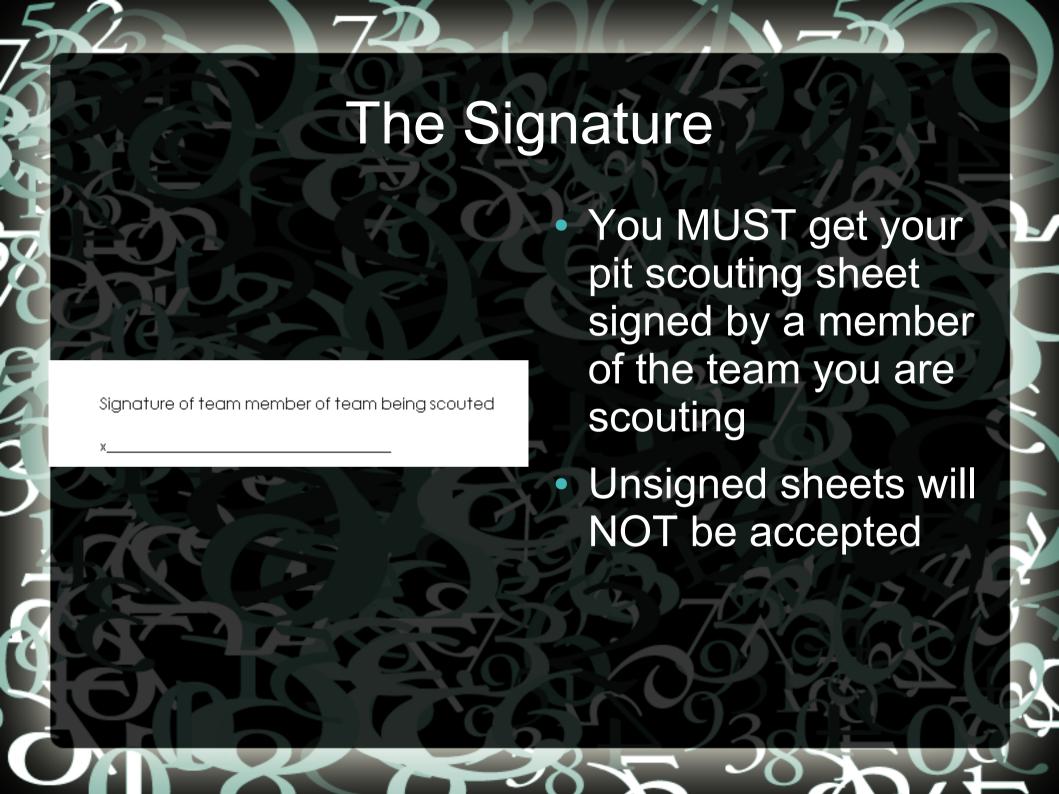
Strategy and Abilities

Furthest zone that they can accurately score from:

Preferred starting zone:\_\_\_\_\_

Preferred human player area:

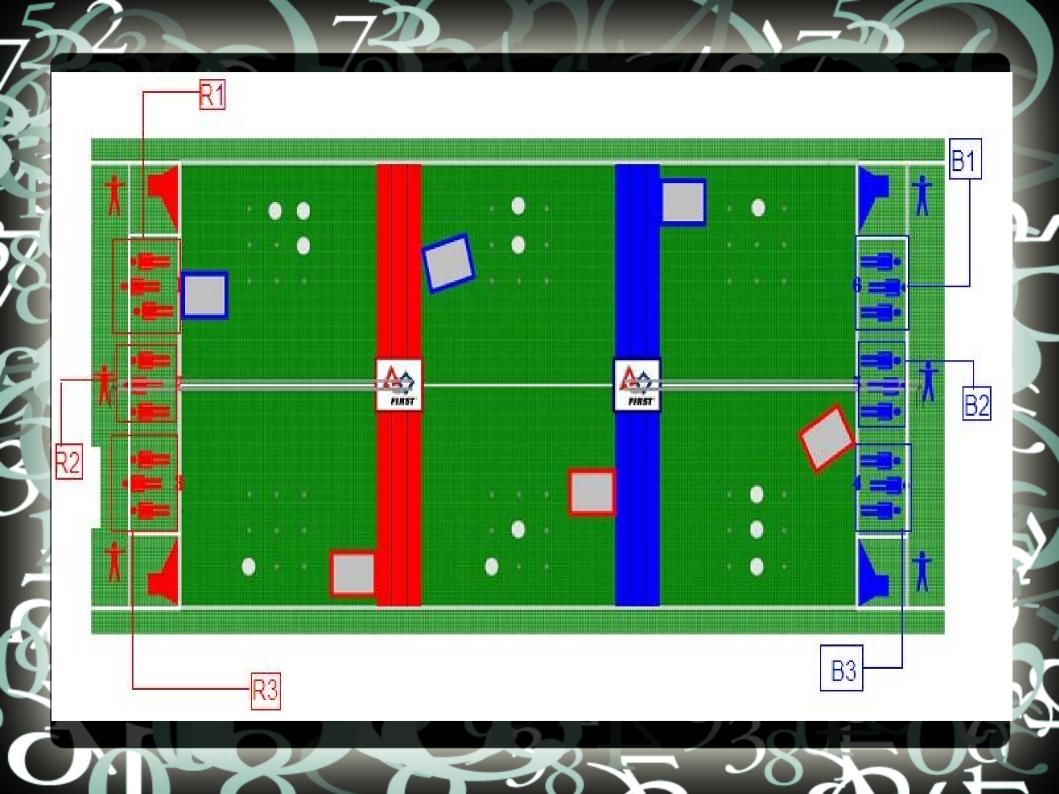
- State what zone your team can ACCURATELY score from at their furthest
- State your team's preferred starting zone
- State where your team's human player prefers to play, side included

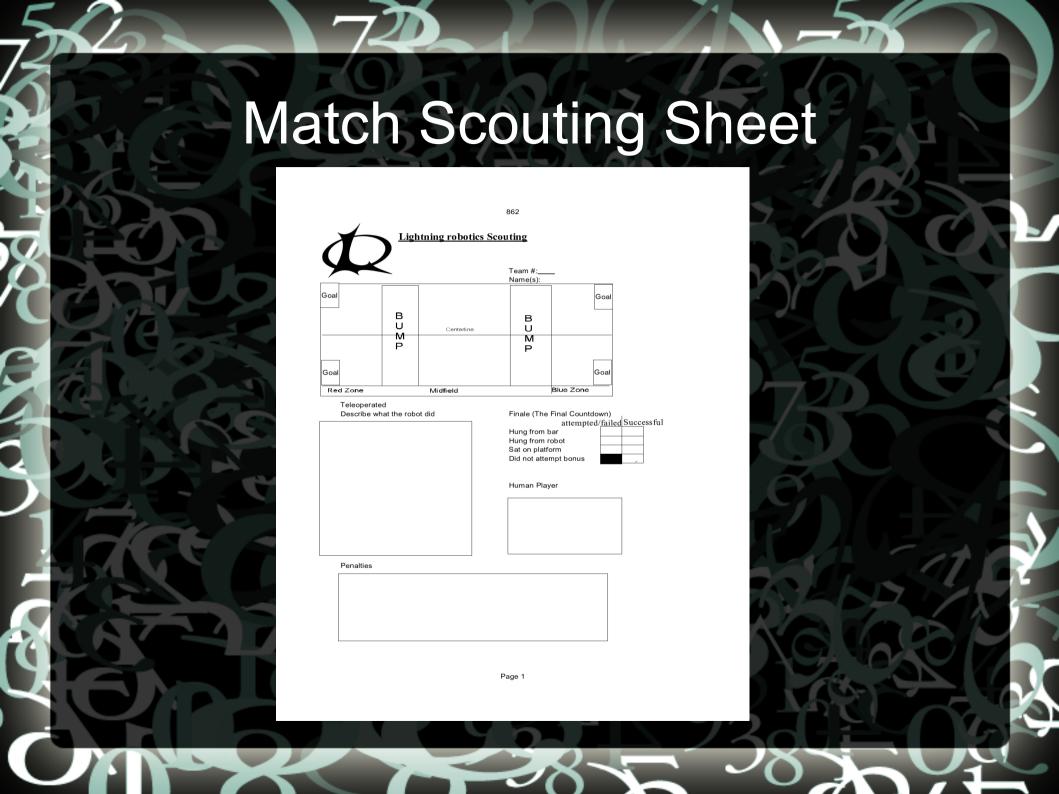


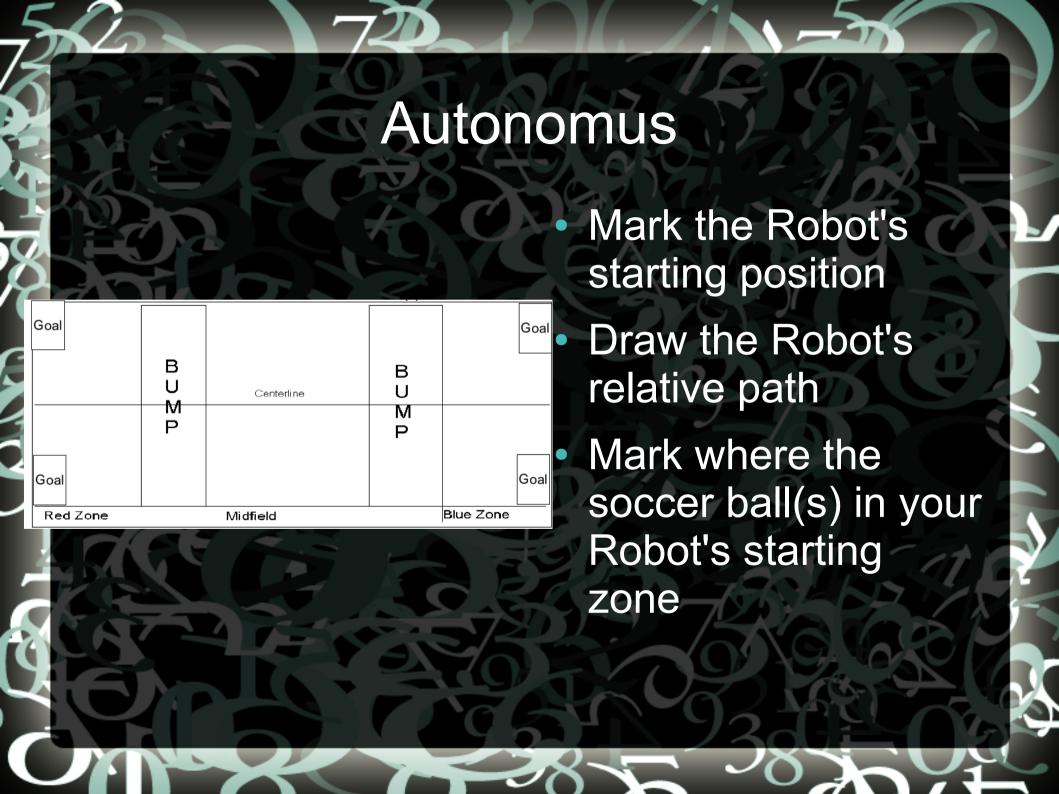
# Determining your team for Match Scouting

- You will be assigned either R1, R2, R3, B1, B2, or B3
- R is for Red alliance
- B is for Blue alliance
- 1,2, and 3 identify the alliance station of your team

 Use the diagram on the next slide to determine what team you are scouting





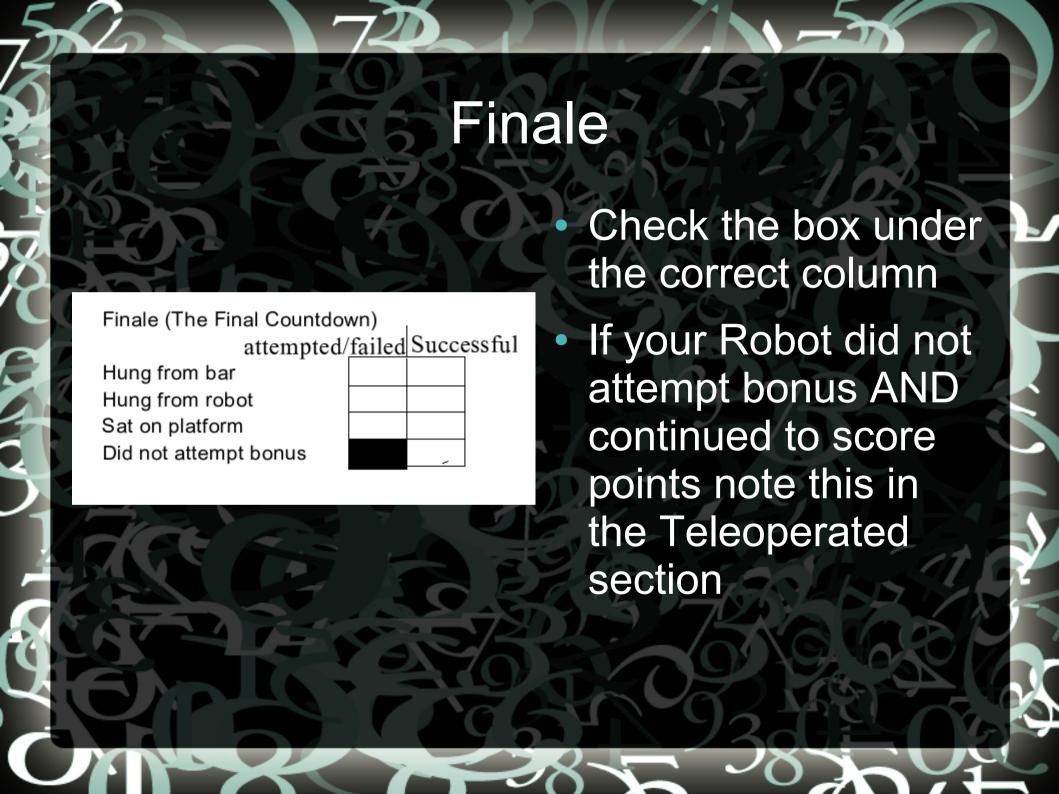


## Teleoperated

Teleoperated

Describe what the robot did

- Describe what the Robot did
- Be sure to include strengths and weaknesses



#### Human Player

- Describe your team's human player
- Be sure to include their position: Corral or Trident
- If Corral, BE SURE to include how they were passing the ball to the trident person

If your Human
Player is at a Corral,
indicate left or right
based on the
diagram on the next
slide

Human Player

## Human Player (cont)

