

Begin.vi
 F:\Drive\Begin.vi

Last modified on 1/17/2019 at 6:03 PM

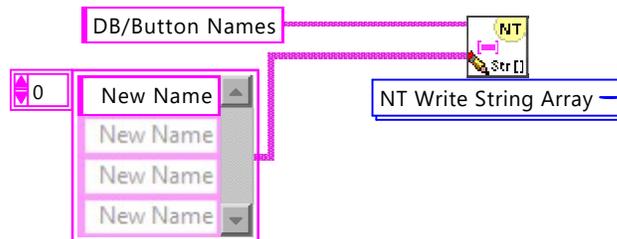
Printed on 1/17/2019 at 7:59 PM

This VI is called before others so you can setup for execution.

The data and I/O allocated here will be made available to the loops for camera, periodic, and to the Auto and TeleOp VIs. To add more I/O, use an Open VI followed by a Refnum Registry Set VI in the other locations.

You may also want to use global variables to communicate between parallel loops.

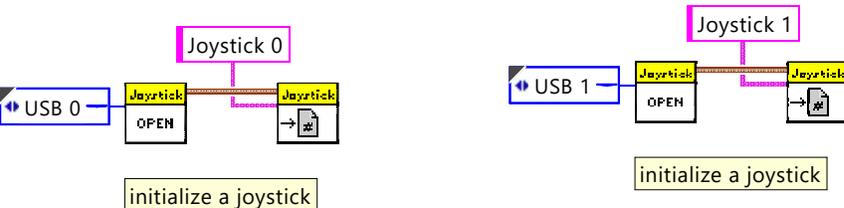
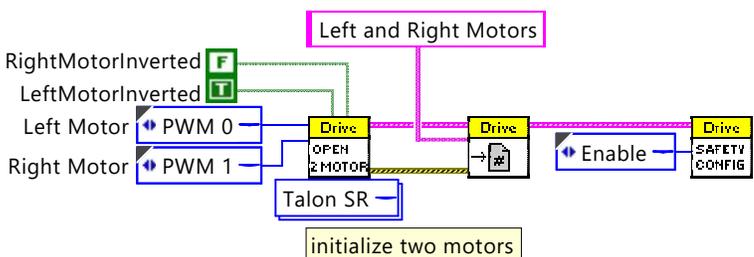
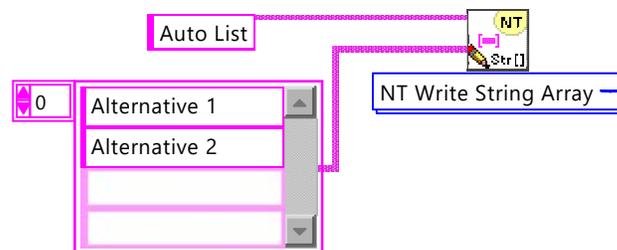
The code below shows how to give controls on the Basic tab more specific names. You can set Button Names, LED Names, Slider Names, and String Names.



Until the communications specify the mode, initialize it to a safe value.



The Drive tab of the default dashboard displays the contents of the Auto List variable. When the user selects a value, it will be written to the Auto Selector variable. You may want to use this, along with other dashboard inputs, to let drivers define the robot's autonomous behavior.



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Double Solenoid Example

