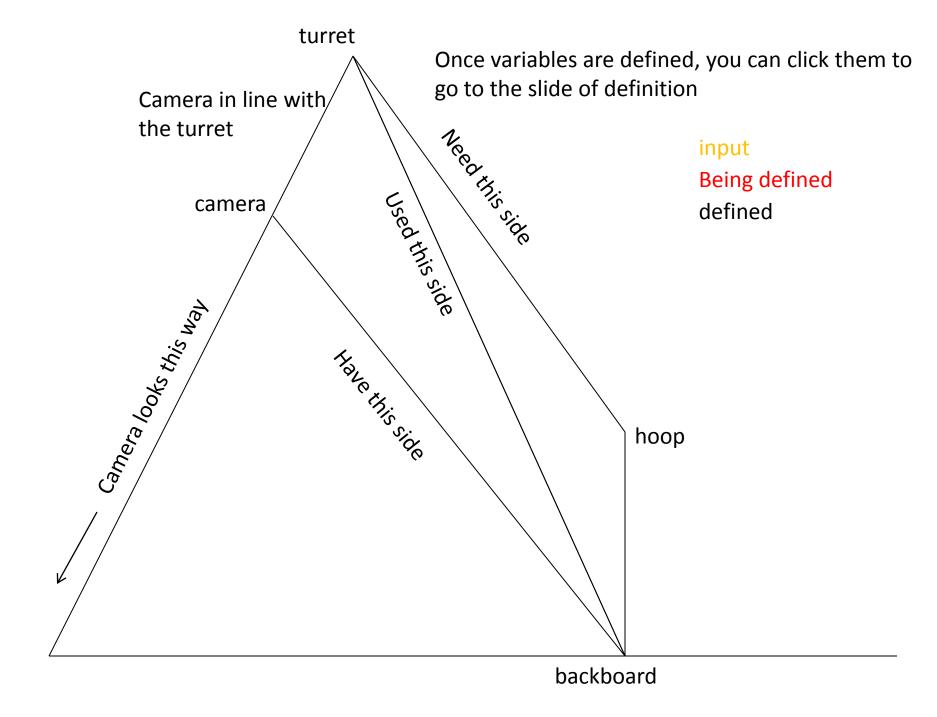
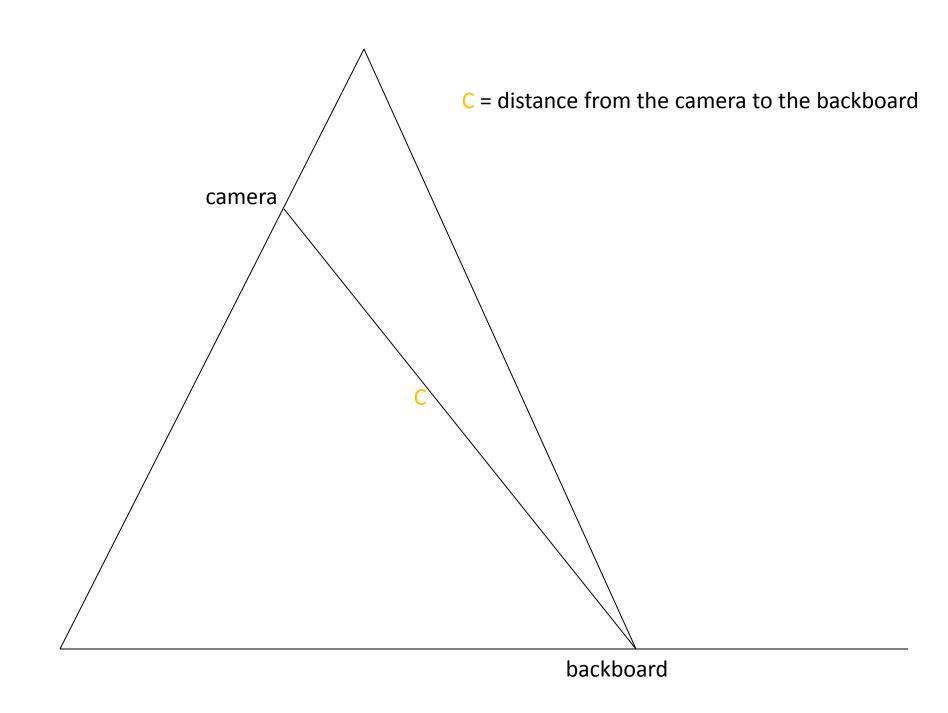
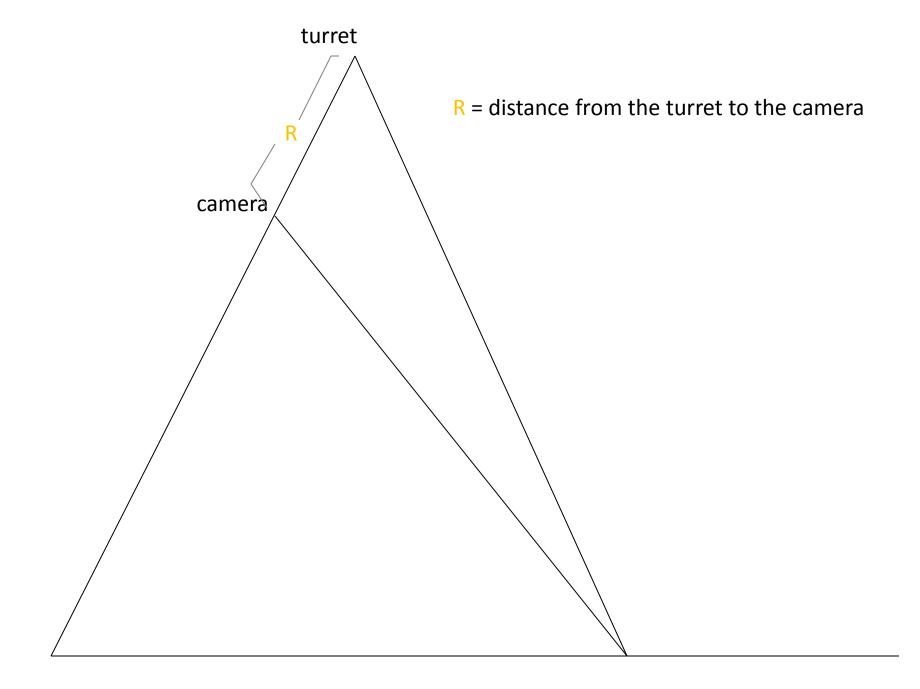
## Finding the Distance Between the Turret and the Hoop

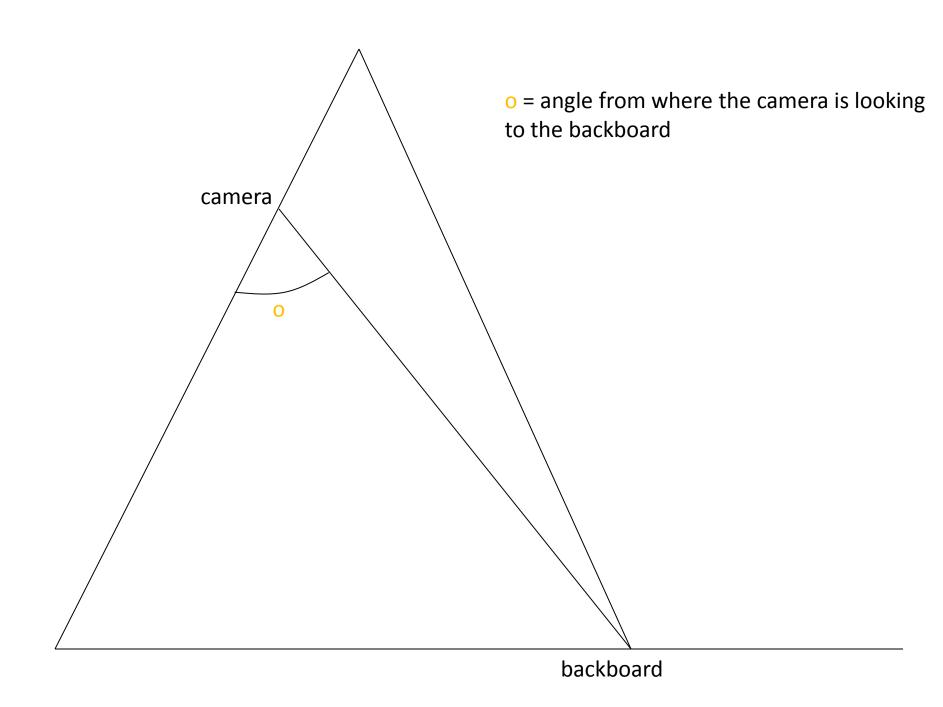
- The camera finds the distance between the camera and the backboard. But, we want the distance from the turret to the hoop.
  - The camera is not always aligned with the turret and backboard with our design
  - Hoop is not always aligned with the turret and backboard.
- The next slides walk through the geometric steps that convert the given camera-backboard distance to the required turret-hoop distance.
  - The variables on each page are hyperlinked to their definitions... have fun.

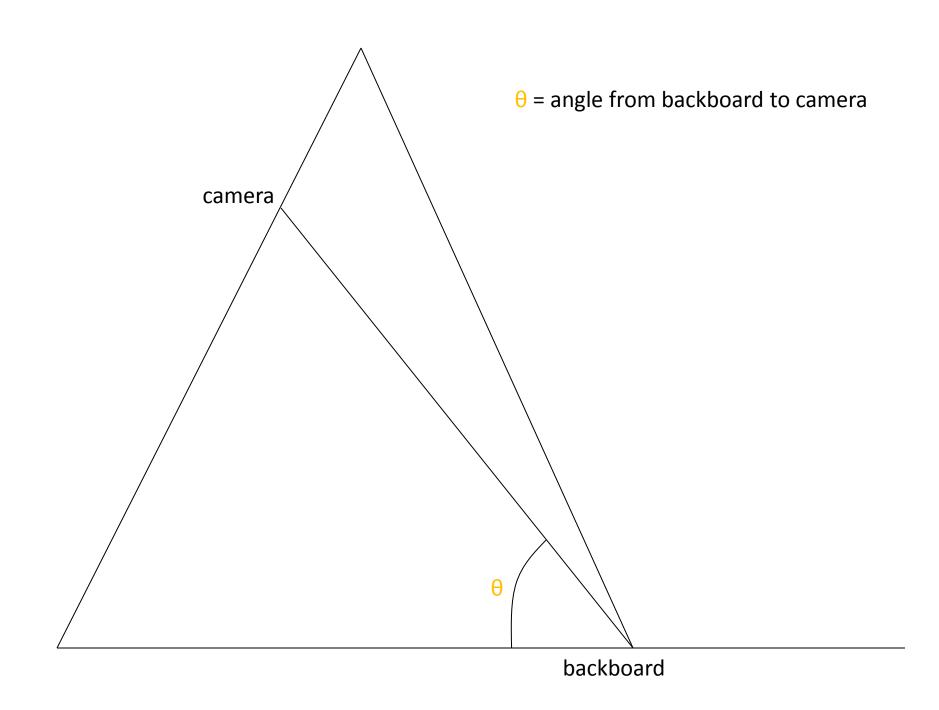
2/1/12 –Knue IRS1318

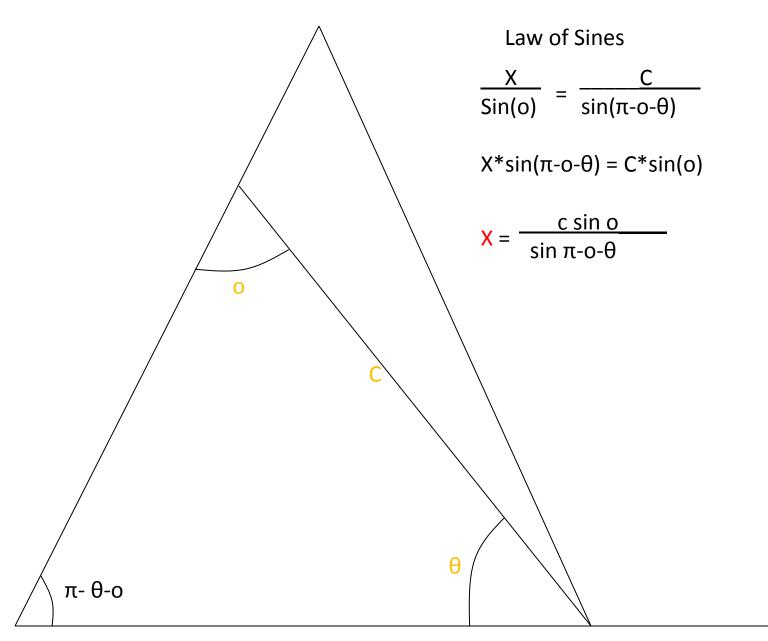


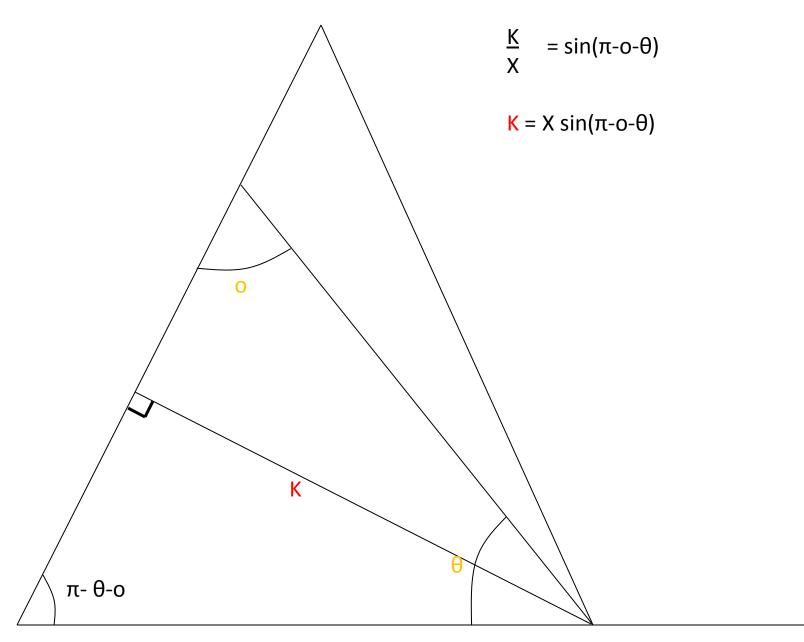




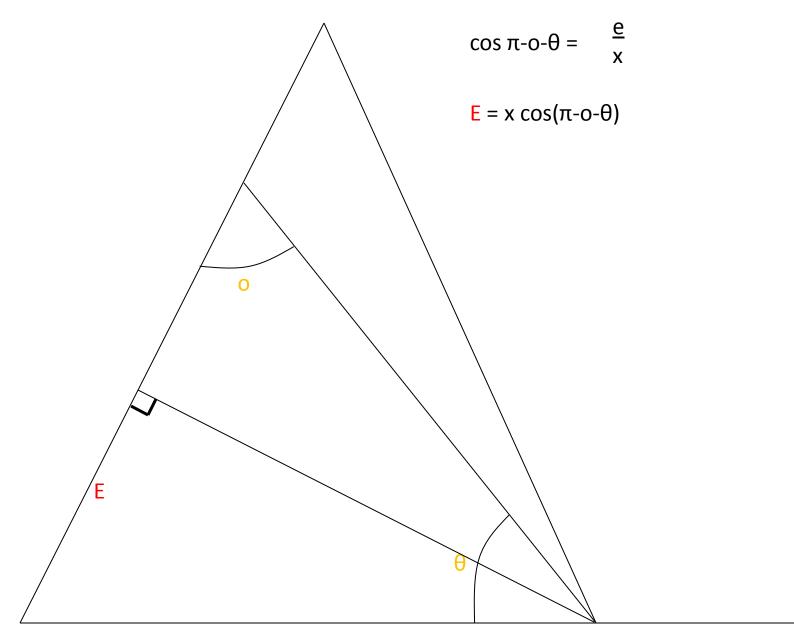




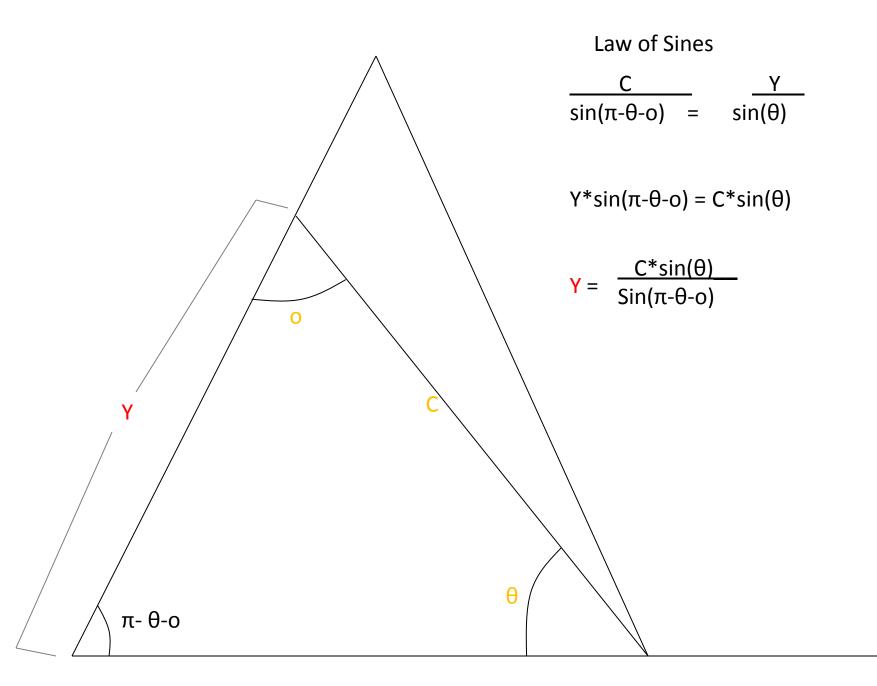


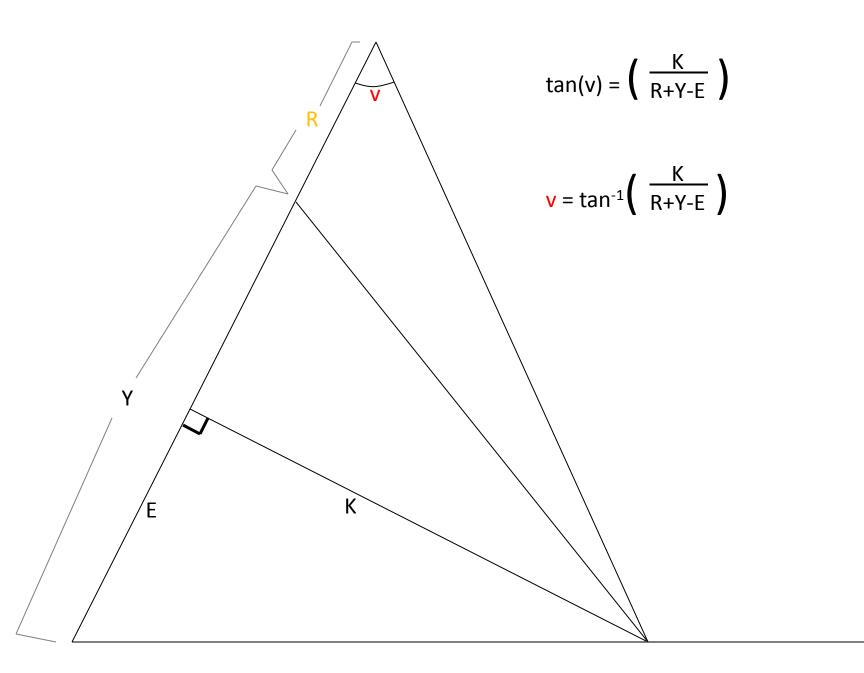


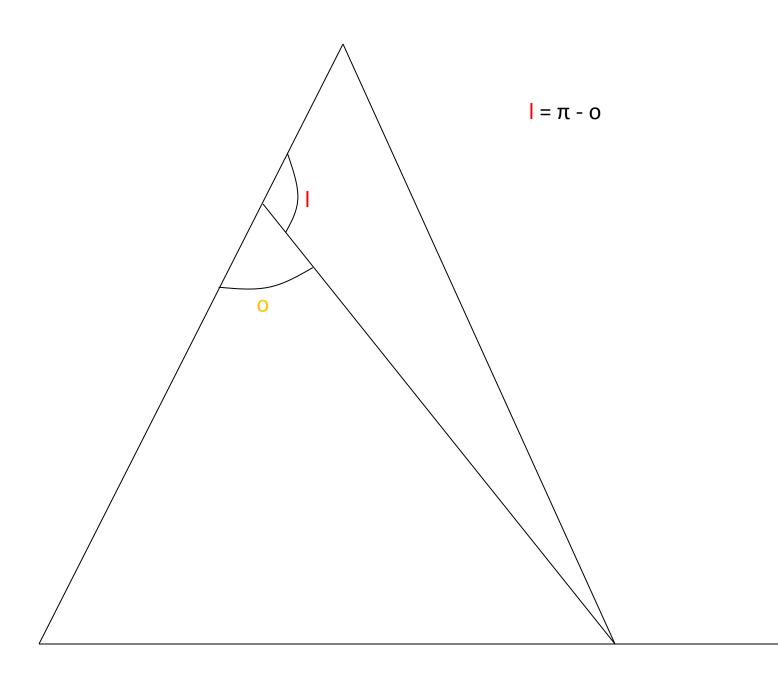
Х

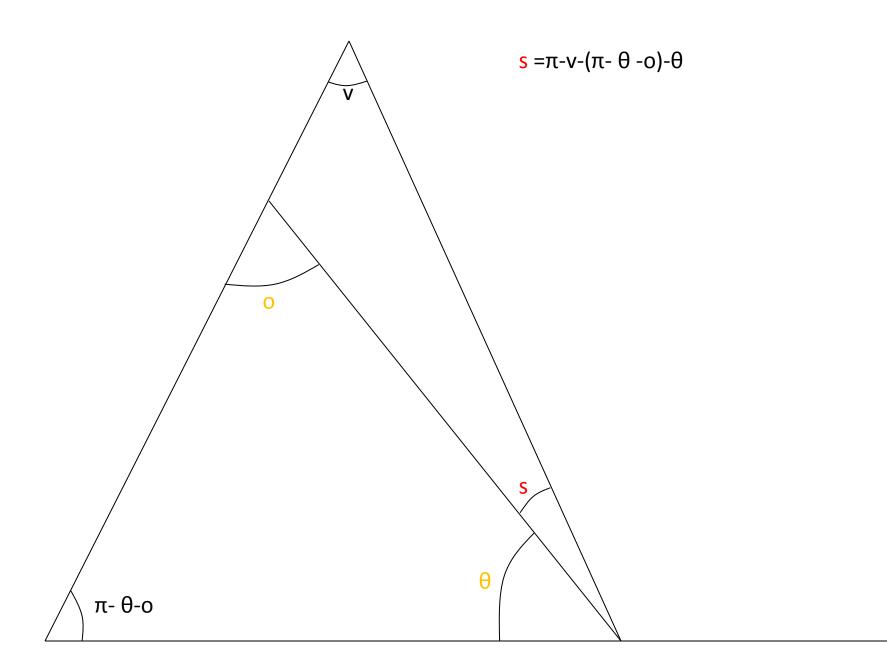


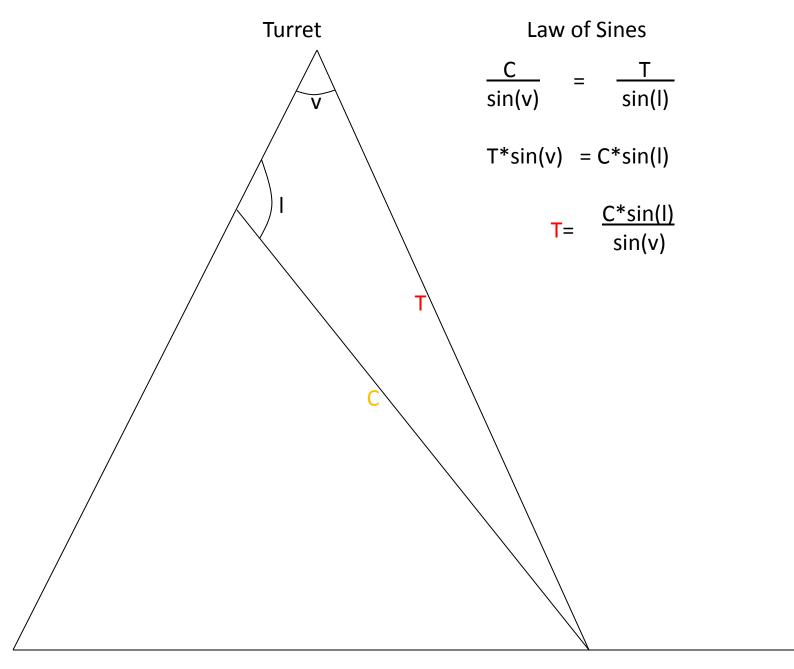
Х



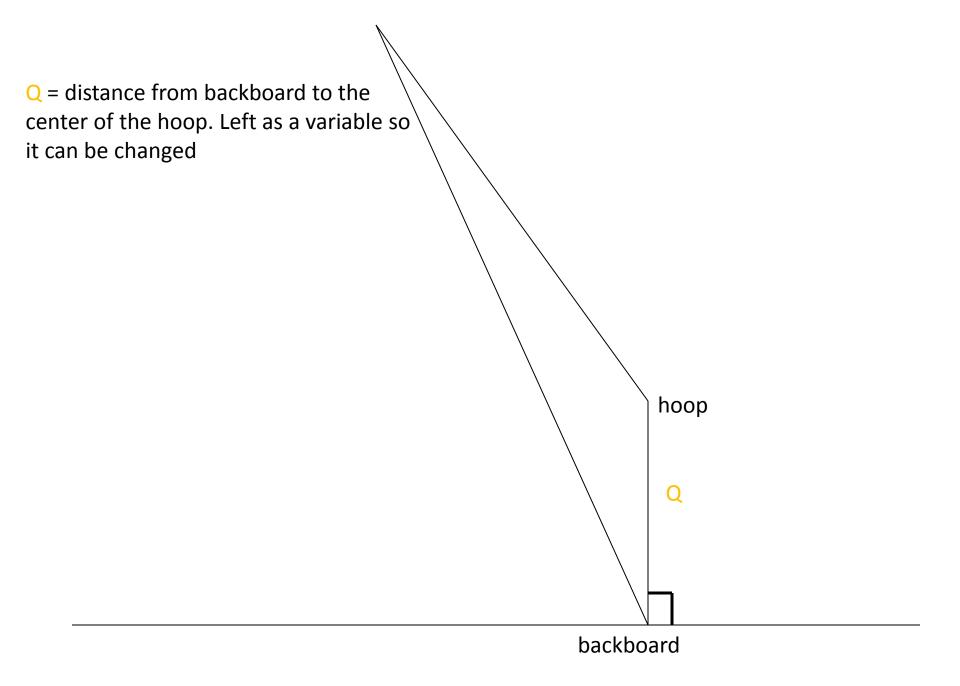


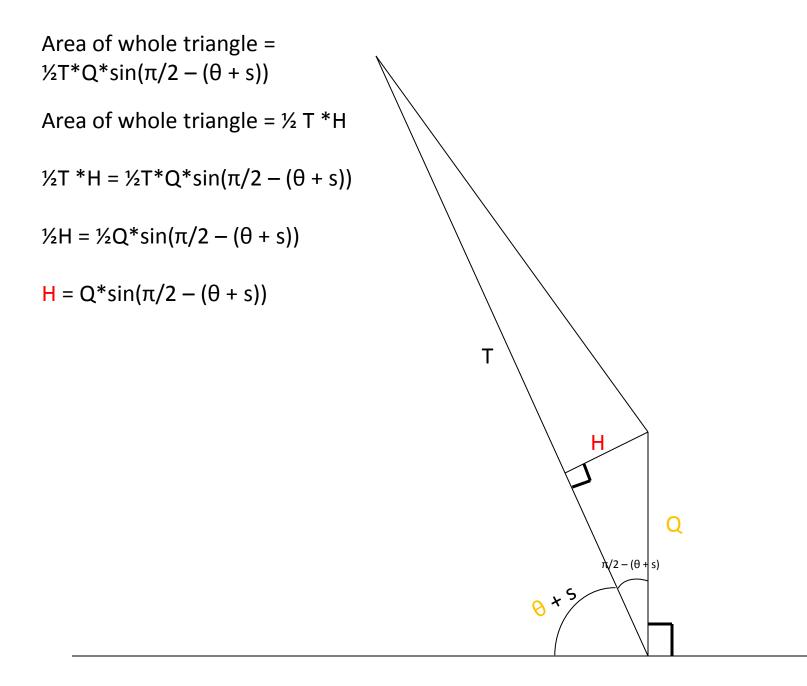






backboard





## Pythagorean theorem

 $Q^{2} = B^{2} + H^{2}$   $B^{2} = Q^{2} - H^{2}$  $B = sqrt(Q^{2} - H^{2})$ 

