

Match:		Red / Blue (circle)	Win / Lose		Penalties:	
Team:			(circle)	(score)		
Autonomous:			Human Player:		Teleoperated:	
Move: Y / N		Made:	Missed:	Shot on:	Scored on:	
Shot on:	Scored on:			Shot:	Scored:	
Shot:	Scored:				Average: %	
Average:		Average: %		Average: %		
Robot Start/Auto move:			End Game:		Empty Cell: Transferred / Carried	Amount:
			Super Cell Exchange: Y / N		Scored by: Human / Robot	
Comments:						
(circle start pos. and trace auto mode)						