

Scouting in *FIRST* Robotics



Novi Kickoff Workshop
January 7th, 2012



**bionic
BARONS**

Andover/Lahser High School
FIRST Robotics Team



Scouting

by

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Outline

- What is Scouting and why is it important?
- What are the different ways to scout?
- What are the different Scouting positions?

- Quick Tutorial in Matrix Algebra
- Review of a method of ranking teams
- Proposed new method of ranking teams
- Features of the Scouting Database

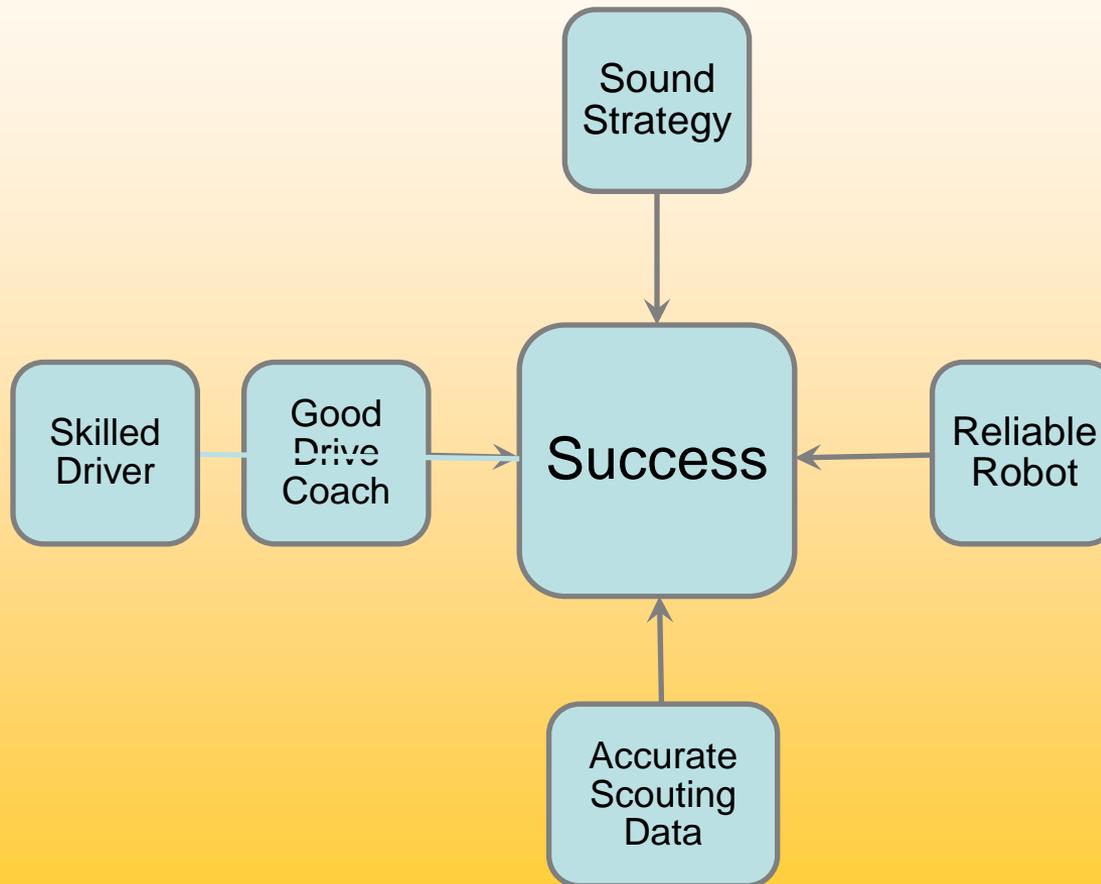


What is the Purpose of Scouting?

- Find out the strength and weakness of your alliance partners and opponents for each match
- Allow you to adjust your tactics of each match based on that information
- Help to create a pick list for alliance selection



Formula for Robot Success





What are the Different Ways to Scout?

Before your Event:

- Scout on teams' websites, videos from youtube and thebluealliance.net

At the Event:

- Pit Scouting (subjective)
- Match Scouting (subjective and objective)
- Videotaping each match for analysis and review
- Calculated Contribution (objective)



Pit Scouting Sheet

Team # _____	Pit Scouting Sheet	Team 2834	
		Initials _____	

Chassis	
Number of Axles	2 or 3 or 4 or _____
Number of Driven Axles	1 or 2 or 3 or _____
Wheel Type	KOP Rubber, KOP traction, traction web top, OMNI, AM Mecanum, Custom Mecanum, other (axle) 1st _____ 2nd _____ 3rd _____ 4th _____ (axle) 1st _____ 2nd _____ 3rd _____ 4th _____
Articulated Axle	Y / N
Speed?	1st Gear _____ 2nd Gear _____

Tube Handling				
Pick up from floor	Y / N			
Pick up from feeder	Y / N			
Ability to Hang <i>*if able to hang on entire level, just circle L/M/H.</i>	Low	Sides	Middle	
	Middle	Sides	Middle	
	High	Sides	Middle	
Manipulator Type:	Arm	Elevator	Other	N/A
Gripper Type:	Claw	Roller	Other	N/A

Minibot	
Have a minibot	Y / N
Able to Deploy	Y / N
Time to top, N/A if no time given	_____

Autonomous			
Starting Position (circle one)	side	middle	
Ubertube hanging position. <i>*if can't, cross out.</i>	Low	Sides	Middle
	Middle	Sides	Middle
	High	Sides	Middle

Notes:



Match Scouting Sheet

Team 2834 Match Scouting Sheet



Match Number	
Team Number	
Starting Position	center / sides

Last Name: _____

	Autonomous	Teleoperated		End Game
	Number of Ubertubes hung	Number of tubes scored	Total tubes transported across center line	Place of minibot
Top		<input type="radio"/>		1 2 3 4
Middle		<input type="radio"/>		(5) failed attempt
Bottom		<input type="radio"/>		didn't attempt

# of Penalties	# of Pinning Penalties

Notes:



Match Scouting Sheet

Aluminum Falcons Scouting System [AFSS]

FRC 2011 - LogoMotion - Championship
Please Print Clearly And Neatly, This Data Will Be Inputted Into Excel

Input Match Data	
Team #	Match #

Enter Specific Team Name & Specific Match Number Above

Autonomous Starting Position		
Outside Left	Middle	Outside Right

Circle The Robot Starting Position For Autonomous

Tube Placement								
		"Left Rack"			"Right Rack"			Options
Top [T]								R
Middle [M]								R+U
Bottom [B]								W
								W+U
								B
								B+U
								U
		A	B	C	D	E	F	

Mark Tube Placement By This Robot Only

Minibot Delivery / Endgame						
Hostbot		Minibot				
Offense	Defense	1st	2nd	3rd	4th	Did Not Make It
		Time to Climb (s)				

Circle What The Robot Achieved In The Endgame

Robot/Human Player Attributes			
Speed of Robot	R	(1)	(2) (3)
Defensive/Offensive	R	Offensive / Equal / Defensive	
Pick-Up From Ground	R	Y	/ N
Received Penalties	R	Y	/ N
Pick-Up From Human Player	R	Y	/ N
Threw Tubes	H	Y	/ N
Pushed Tubes Through Wall	H	Y	/ N
Maneuverability	R	(1)	(2) (3)

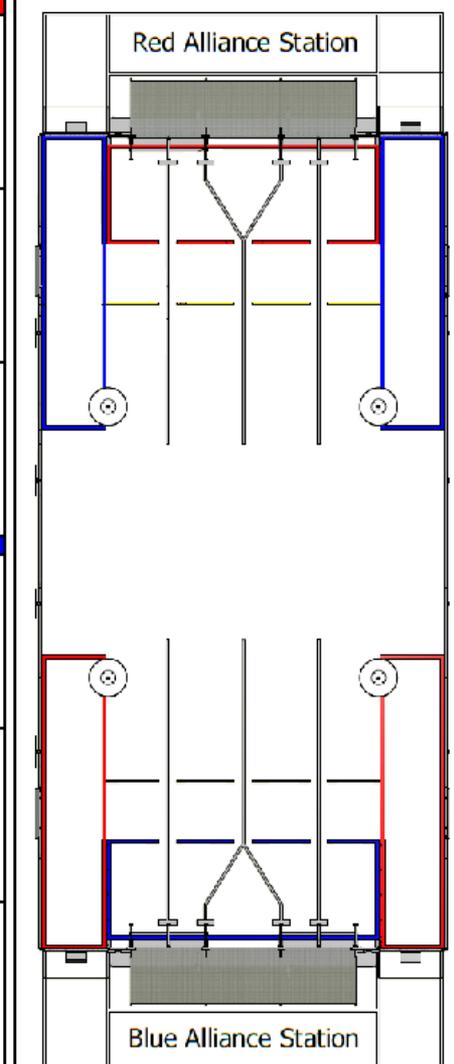
Please Circle Your Observations Above

Comments
Please Provide Brief Comments On Robot Design & Performance

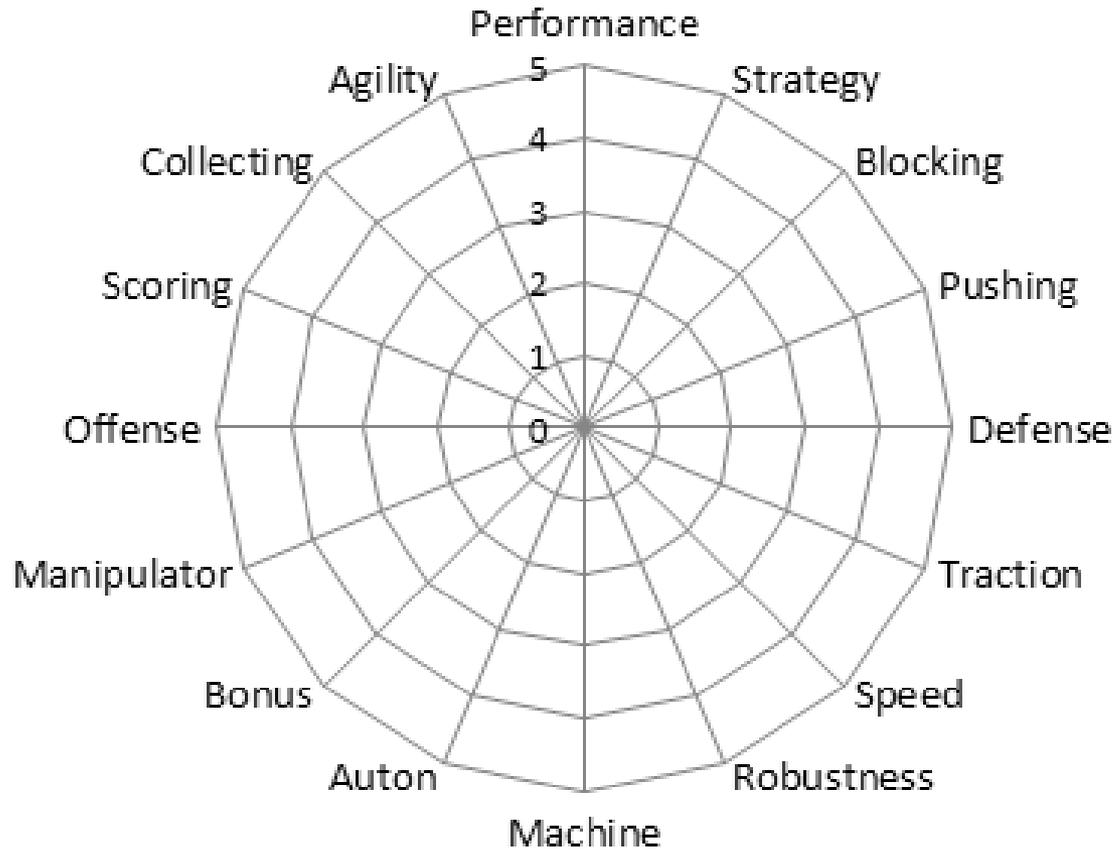


Pre-Match Sheet

Pre-Match Scouting Sheet			
Red Alliance			
Red Alliance Member #1			
Team Number	Notes:	Drivetrain Type	
Autonomous Mode(s)		4WD	
		6WD	
		3WD	
		Omni	
		Mecanum	
		Crab	
		Hybrid	
Red Alliance Member #2			
Team Number	Notes:	Drivetrain Type	
Autonomous Mode(s)		4WD	
		6WD	
		3WD	
		Omni	
		Mecanum	
		Crab	
		Hybrid	
Red Alliance Member #3			
Team Number	Notes:	Drivetrain Type	
Autonomous Mode(s)		4WD	
		6WD	
		3WD	
		Omni	
		Mecanum	
		Crab	
		Hybrid	
Blue Alliance			
Blue Alliance Member #1			
Team Number	Notes:	Drivetrain Type	
Autonomous Mode(s)		4WD	
		6WD	
		3WD	
		Omni	
		Mecanum	
		Crab	
		Hybrid	
Blue Alliance Member #2			
Team Number	Notes:	Drivetrain Type	
Autonomous Mode(s)		4WD	
		6WD	
		3WD	
		Omni	
		Mecanum	
		Crab	
		Hybrid	
Blue Alliance Member #3			
Team Number	Notes:	Drivetrain Type	
Autonomous Mode(s)		4WD	
		6WD	
		3WD	
		Omni	
		Mecanum	
		Crab	
		Hybrid	



Pre-Match Sheet



Pre-Match Sheet

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P		
1	MichiganState																	
2	setup link																	
3	Red Alliance								projected score		Blue Alliance							
4									2	7								
5	2834				Projected OPR	1.7	Proj. CCWM	-0.6	548				Projected OPR	1.0	Proj. CCWM	0.6		
6					Current OPR	2.1	Avg Seed Score	2.1					Current OPR	1.8	Avg Seed Score	2.3		
7	Red 1					robot speed	1.8182	auto % handled	57%					robot speed	1.6364	auto % handled	40%	Blue 1
8						cross zone	1	auto % scored	43%					cross zone	1	auto % scored	4%	
9						tele ball handle	5.0909	tele ball scored	4.1818					tele ball handle	2.0909	tele ball scored	0.7273	
10						tele ball scored	4.1818	finale ball handl	1.0909					tele ball scored	0.7273	finale ball handl	0.1818	
11						ball control	1.1818	finale ball score	1					ball control	1.7273	finale ball score	0.1818	
12						avg ball handler	6.1818	elevate/suspen	0					avg ball handler	2.2727	elevate/suspen	0	
13						start zone	1.2727	# of penalties	0					start zone	2.2727	# of penalties	0	
14						Auton:		# of penalties	0					Auton:		# of penalties	0	
15					Auton:		# of penalties	0					Auton:		# of penalties	0		
16					Finale:		# of penalties	0					Finale:		# of penalties	0		
17	3115				Projected OPR	0.4	Proj. CCWM	-0.7	2960				Projected OPR	0.2	Proj. CCWM	-0.7		
18					Current OPR	1.9	Avg Seed Score	2.2					Current OPR	0.8	Avg Seed Score	2.4		
19	Red 2					robot speed	1.9091	auto % handled	58%					robot speed	1.9	auto % handled	43%	Blue 2
20						cross zone	1.2857	auto % scored	26%					cross zone	1	auto % scored	29%	
21						tele ball handle	1.7273	tele ball scored	1.2727					tele ball handle	3.1818	tele ball scored	2.7273	
22						tele ball scored	1.2727	finale ball handl	0.0909					tele ball scored	2.7273	finale ball handl	0.1818	
23						ball control	1.6364	finale ball score	0.0909					ball control	1.8	finale ball score	0.1818	
24						avg ball handler	1.8182	elevate/suspen	0					avg ball handler	3.3636	elevate/suspen	0	
25						start zone	1.7273	# of penalties	0.0909					start zone	1.2727	# of penalties	0.0909	
26						Auton:		# of penalties	0					Auton:		# of penalties	0	
27					Auton:		# of penalties	0					Auton:		# of penalties	0		
28					Finale:		# of penalties	0					Finale:		# of penalties	0		
29	815				Projected OPR	1.2	Proj. CCWM	-0.6	66				Projected OPR	0.7	Proj. CCWM	-0.3		
30					Current OPR	-1.5	Avg Seed Score	1.2					Current OPR	3.9	Avg Seed Score	2.7		
31	Red 3					robot speed	2.1429	auto % handled	0%					robot speed	1.8182	auto % handled	77%	Blue 3
32						cross zone	1.1429	auto % scored	0%					cross zone	1.1	auto % scored	29%	
33						tele ball handle	1.5556	tele ball scored	1.1111					tele ball handle	1.5	tele ball scored	0.3333	
34						tele ball scored	1.1111	finale ball handl	0					tele ball scored	0.3333	finale ball handl	0.0833	
35						ball control	2.1429	finale ball score	0					ball control	1.5455	finale ball score	0.0833	
36						avg ball handler	1.5556	elevate/suspen	0					avg ball handler	1.5833	elevate/suspen	1	
37						start zone	1.5556	# of penalties	0.1111					start zone	2.9167	# of penalties	0.25	
38						Auton:		# of penalties	0					Auton:		# of penalties	0	
39					Auton:		# of penalties	0					Auton:		# of penalties	0		
40					Finale:		# of penalties	0					Finale:		# of penalties	0		

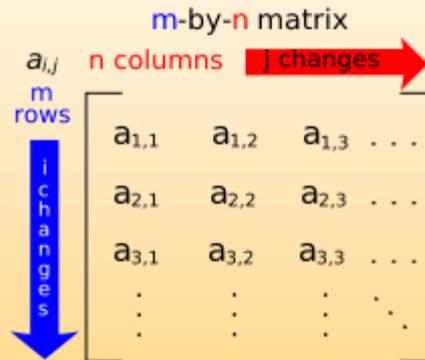


What are the Different Scouting Positions?

- Scouting mentor
- Head scout
- Pit scout
- Match scout
- Video scout
- Data analyst

Quick Tutorial in Matrices

In mathematics, a matrix (plural matrices) is a rectangular table of elements (or entries), which may be numbers or, more generally, any abstract quantities that can be added and multiplied. Matrices are commonly used to describe linear equations.



The horizontal lines in a matrix are called rows and the vertical lines are called columns. A matrix with m rows and n columns is called an m -by- n matrix (written $m \times n$) and m and n are called its dimensions. The dimensions of a matrix are always given with the number of rows first, then the number of columns.

Quick Tutorial in Matrices

Matrix addition

$$\begin{bmatrix} 1 & 3 & 1 \\ 1 & 0 & 0 \\ 1 & 2 & 2 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 5 \\ 7 & 5 & 0 \\ 2 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1+0 & 3+0 & 1+5 \\ 1+7 & 0+5 & 0+0 \\ 1+2 & 2+1 & 2+1 \end{bmatrix} = \begin{bmatrix} 1 & 3 & 6 \\ 8 & 5 & 0 \\ 3 & 3 & 3 \end{bmatrix}$$

Matrix multiplication

$$\begin{bmatrix} 1 & 0 & 2 \\ -1 & 3 & 1 \end{bmatrix} \times \begin{bmatrix} 3 & 1 \\ 2 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} (1 \times 3 + 0 \times 2 + 2 \times 1) & (1 \times 1 + 0 \times 1 + 2 \times 0) \\ (-1 \times 3 + 3 \times 2 + 1 \times 1) & (-1 \times 1 + 3 \times 1 + 1 \times 0) \end{bmatrix} = \begin{bmatrix} 5 & 1 \\ 4 & 2 \end{bmatrix}$$

2×3
 3×2
 2×2

$$\begin{bmatrix} 1 & 0 & 2 \\ -1 & 3 & 1 \end{bmatrix} \times \begin{bmatrix} 3 & 1 \\ 2 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} (1 \times 3 + 0 \times 2 + 2 \times 1) & (1 \times 1 + 0 \times 1 + 2 \times 0) \\ (-1 \times 3 + 3 \times 2 + 1 \times 1) & (-1 \times 1 + 3 \times 1 + 1 \times 0) \end{bmatrix}$$

Quick Tutorial in Matrices

The following is a system of equations with two equations and two unknowns.

$$2x + 5y = 16$$

$$x + 3y = 9$$

This can be rewritten in matrix form

$$\begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix} = \begin{Bmatrix} 16 \\ 9 \end{Bmatrix}$$
$$\begin{Bmatrix} x \\ y \end{Bmatrix} = \begin{bmatrix} 3 & -5 \\ -1 & 2 \end{bmatrix} \begin{Bmatrix} 16 \\ 9 \end{Bmatrix}$$
$$= \begin{Bmatrix} 3 \\ 2 \end{Bmatrix}$$



Offensive Power Rating

From the Chief Delphi forum, the earliest I found the use of the term Offensive Power Rating (OPR) was by Scott Weingart (“sw293”) in his April 2006 posting. I think he first coined this term OPR and explained how it is calculated in the Chief Delphi post:
<http://www.chiefdelphi.com/forums/showpost.php?p=484220&postcount=19>

Karthik Kanagasabapathy from Team 1114 did the same calculation and called it Calculated Contribution. He first published it in 2008.

“Bongle” from Team 2702 and Guy Davidson from Team 8 implemented the calculation of OPR from “sw293” and published a lot of results on Chief Delphi before the Championship in 2008.



How to Calculate OPR?

Assume team i , j and k are three teams in an alliance and they scored p points in that match. Then we can write

$$x_i + x_j + x_k = p, \text{ where } x_i \text{ is the score contributed by team } i$$

Assume team i played with team m and n in another alliance and they score q points in that match. Then we can write

$$x_i + x_m + x_n = q$$

If we add all the matches that team i was involved in, we get

$$2x_i + x_j + x_k + x_m + x_n = p + q = B_i$$

If we put them in row i of an $N \times N$ matrix A , where N is the total number of teams in that regional, and repeat that for each team, we get

How to Calculate OPR?

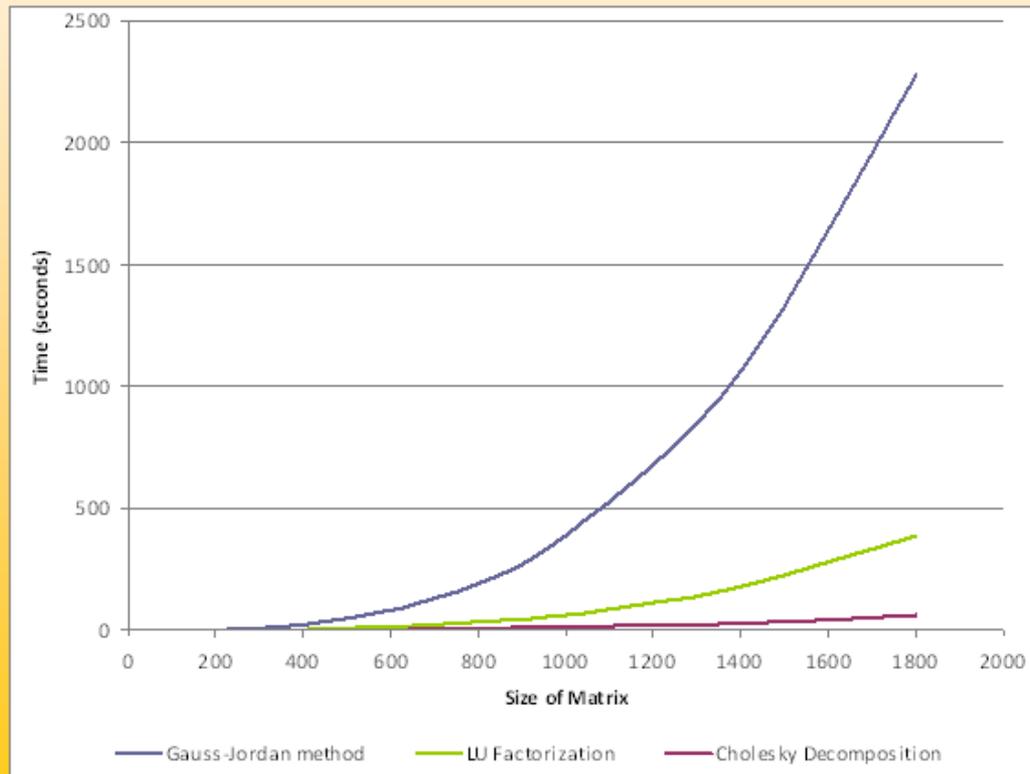
$$2x_i + x_j + x_k + x_m + x_n = p+q = B_i$$

$$\begin{array}{c}
 \\
 i \\
 j \\
 k \\
 l \\
 m \\
 n
 \end{array}
 \begin{array}{c}
 \\
 i \\
 j \\
 k \\
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 \begin{array}{c}
 \\
 n
 \end{array}
 \left\{ \begin{array}{c} x_i \\ x_j \\ x_k \\ x_l \\ x_m \\ x_n \end{array} \right\} = \left\{ \begin{array}{c} B_i \\ B_j \\ B_k \\ B_l \\ B_m \\ B_n \end{array} \right\}$$

$$[A] \{x\} = \{B\}$$

How to Calculate OPR?

Since the matrix A is symmetric and positive definite, we can use Cholesky decomposition to solve for x . The result x is the contribution of each team to each of their alliance. The number is known as the Offensive Power Rating of each team.





A Proposed New Method

The drawback of the Offensive Power Rating is that it completely ignores the contribution of defense. Jay Lundy from Team 254 has proposed another method that takes into account both defense and offense. Please refer to Chief Delphi post <http://www.chiefdelphi.com/forums/showpost.php?p=733759&postcount=160>

However it will result in a rectangular matrix which is harder to solve. Also the offense and defense numbers may be hard to interpret.

Hence I am proposing a new method that takes into account both offense and defense directly and still have a symmetric and positive definite matrix.



A Proposed New Method

Once you understand how to calculate OPR, it is fairly simple to calculate this new rating. It is based on the winning margin of each match rather than the points scored. So instead of adding up all the points of all the matches and put into B_i , you add up all the winning margins and put into B_i .

$$2x_i + x_j + x_k + x_m + x_n = p+q = B_i$$

I call this new rating CCWM which simply stands for Calculated Contribution to Winning Margin.

Notice that some teams have negative CCWM and if you add up all the CCWM of all the teams in the regional, you will get zero.



A Proposed New Method

This CCWM gives credit to teams that play good defense. In games where your team's Match Ranking Points is based on your opposing alliance's score, this should still be valid since you want to score as many points as possible. The only time it does not work is if your team is allowed to intentionally score points for your opponents' alliance. Even so, this does not occur very often unless there is a very big lead and you know you will win for sure. However in a two minutes game, after establishing a big lead, the amount of time left to intentionally score points for your opponent is limited.



Comparison between OPR and CCWM

Using 2008 Regional data, I found that CCWM is as good as OPR in terms of predicting the outcome of the elimination matches.

CCWM seems to correlate better than OPR in terms of actual teams selected as alliances even though there are many factors that affect how teams are selected.

For a game like the one in 2008 where there are only two balls to hurdle and the third team can either run laps to score points or play defense, the first pick should probably be one who can score as many points as possible. Hence OPR can be a good criteria. For the second pick, I think that using CCWM will have a better chance than using OPR to unearth a gem that is overlooked by other teams.

My conclusion is OPR and CCWM both have advantages and disadvantages. It depends on the game and how the match ranking points are scored.



A Note on DPR and PMR

At around the same time that I developed CCWM, other people have proposed calculating DPR which stands for Defensive Power Rating and PMR which stands for Plus/Minus Rating. These were proposed by a number of people but made popular by “Bongle”.

DPR is calculated similar to OPR except the vector B is the sum of all the opposing alliances’ scores instead of your alliances’ scores. PMR can be calculated by subtracting DPR from OPR.

Jesse Knight of Team 1885 was the first to notice that CCWM and PMR are numerically identical and he verified it with his program. Subsequently, I published a proof why they are numerically the same at

<http://www.chiefdelphi.com/forums/showpost.php?p=835222&postcount=48>

Hence $DPR = OPR - CCWM$



The Interpretation of OPR

OPR does not predict what a team (robot and human player) can score. It is the calculated contribution by that team on average to all the matches they were involved in to their alliance partners. A team that has high OPR score means that every time they are on the field, good things happen to that alliance meaning high score. Some of the possibilities are:

- 1) their robot score a lot of points
- 2) their human player score a lot of points (2009)
- 3) their presence allow their alliance partners to score a lot of points which they don't normally do as well.
- 4) they have on average stronger partners and weaker opponents by the luck of the draw than other teams.

A low OPR is just the opposite.



The Interpretation of CCWM

CCWM is the calculated contribution to the winning margins of the matches the team was involved in. A negative CCWM means the team is a liability to their partners. A team with negative CCWM should not be picked as alliance partners.

A team that has high CCWM means that every time they are on the field, good things happen to that alliance and in this case it means winning by a big margin. Some of the possibilities are:

- 1) they score more points on others than others score on them
- 2) their presence allow their alliance to score more points on others than others score on them. This could be from playing defense or help pin an opposing robot so their alliance partner can score more (2009)
- 3) they do not incur much penalties.
- 4) they have on average stronger partners and weaker opponents by the luck of the draw than other teams.



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Features of Team 2834 Scouting Database



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Questions?

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